

The Quadratic Linear Ordering Problem

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1 Motivation

In the linear ordering problem (LOP), we see an acyclic tournament subdigraph of maximum total edge weight. This assumes that pairwise comparisons contribute independently to the objective, ignoring higher-order consistency across multiple comparisons. For example, consider the following data, where the (i, j) entry denotes how many times team i beat team j :

$$A = \begin{bmatrix} 0 & 2 & 6 & 5 \\ 2 & 0 & 4 & 1 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

The objective function for the corresponding LOP is given by

$$\begin{aligned} z &= 2x_{12} + 6x_{13} + 5x_{14} + 4x_{23} + 1x_{24} + 3x_{34} + 2(1 - x_{12}) \\ &= 2 + 6x_{13} + 5x_{14} + 4x_{23} + 1x_{24} + 3x_{34}. \end{aligned}$$

Hence, $z \leq 21$. Moreover, both rankings $(1, 2, 3, 4)$ and $(2, 1, 3, 4)$ are optimal with objective value $z = 21$. However, the ranking $(1, 2, 3, 4)$ is more consistent than the ranking $(2, 1, 3, 4)$ with respect to the data since team 1 won more games than team 2 against teams 3 and 4.

2 The Quadratic Linear Ordering Problem

Consider a digraph of order n , where each edge (i, j) has weight $a_{ij} \geq 0$. In the LOP, the weight a_{ij} defines the benefit of selecting i to precede j in the ranking. In the quadratic linear ordering problem, denoted QLOP, the weight $b_{ij,kl}$ defines the benefit of selecting i to precede j and k to precede l . Defined below is the QLOP which seeks an acyclic tournament subdigraph that maximizes the total edge weight a_{ij} plus the total mixing weight $b_{ij,kl}$.

$$\begin{aligned} \text{maximize} \quad & z = \sum_{i \neq j} a_{ij}x_{ij} + \sum_{i \neq j} \sum_{k \neq l} b_{ij,kl}x_{ij}x_{kl} \\ \text{subject to} \quad & x_{ij} + x_{ji} = 1, \quad \forall i < j, \\ & x_{ij} + x_{jk} + x_{ki} \leq 2, \quad \forall i < j, \quad i < k, \quad j \neq k, \\ & x_{ij} \in \{0, 1\}, \quad \forall i \neq j. \end{aligned}$$

Example

We now consider how the QLOP can be used to differentiate between the two optimal rankings in Section 1. For each edge (i, j) define the dominance margin to be

$$m_{ij} = a_{ij} - a_{ji}$$

For each pair of edges (i, j) and (j, k) define the mixing term

$$b_{ij,jk} = m_{ik} - m_{jk},$$

and define all other mixing terms to be zero. We scale the non-zero mixing terms by a small $\epsilon > 0$ so that the objective seeks to optimize the total edge weight before optimizing the total mixing weight. For example,

$$\epsilon = \frac{\min\{a_{ij} : i \neq j, a_{ij} \neq 0\}}{2 \max\{|b_{ij,jk}| : i \neq j, j \neq k\}},$$

will ensure that no quadratic term can outweigh a linear term in the objective. Then, the objective for the QLOP in this example can be written as follows

$$z = \sum_{i \neq j} a_{ij} x_{ij} + \epsilon \sum_{i \neq j} \sum_{j \neq k} b_{ij,jk} x_{ij} x_{jk}.$$

Since the objective function seeks to optimize the total edge weight before optimizing the total mixing weight, we only need to consider the quadratic terms on the two optimal rankings $(1, 2, 3, 4)$ and $(2, 1, 3, 4)$. For the ranking $(1, 2, 3, 4)$ the corresponding quadratic terms are

$$\begin{aligned} b_{12,23} &= m_{13} - m_{23} = 6 - 4 = 2, \\ b_{12,24} &= m_{14} - m_{24} = 5 - 1 = 4, \\ b_{13,34} &= m_{14} - m_{34} = 5 - 3 = 2, \\ b_{23,34} &= m_{24} - m_{34} = 1 - 3 = -2. \end{aligned}$$

For the ranking $(2, 1, 3, 4)$ the corresponding quadratic terms are

$$\begin{aligned} b_{21,13} &= m_{23} - m_{13} = 4 - 6 = -2, \\ b_{21,14} &= m_{24} - m_{14} = 1 - 5 = -4, \\ b_{23,34} &= m_{24} - m_{34} = 1 - 3 = -2, \\ b_{13,34} &= m_{14} - m_{34} = 5 - 3 = 2. \end{aligned}$$

Therefore, the ranking $(1, 2, 3, 4)$ has a quadratic sum of 6ϵ and the ranking $(2, 1, 3, 4)$ has a quadratic sum of -6ϵ . Since $\epsilon > 0$ it follows that the ranking $(1, 2, 3, 4)$ is the unique optimal ranking for the QLOP.

3 Linearization

Since the quadratic objective makes the problem difficult to solve directly, we introduce a standard linearization with the variables $y_{ij,kl} \in \{0, 1\}$ and constraints

$$y_{ij,kl} \leq x_{ij}, \tag{1}$$

$$y_{ij,kl} \leq x_{kl}, \tag{2}$$

$$y_{ij,kl} \geq x_{ij} + x_{kl} - 1. \tag{3}$$

Note that, if $x_{ij} = 0$ or $x_{kl} = 0$ then $y_{ij,kl} = 0$ by constraints (1)–(2). Conversely, if $y_{ij,kl} = 0$ then constraint (3) implies that $x_{ij} + x_{kl} \leq 1$, so $x_{ij} = 0$ or $x_{kl} = 0$. Also, if $x_{ij} = 1$ and $x_{kl} = 1$ then $y_{ij,kl} = 1$ by constraint (3). Conversely, if $y_{ij,kl} = 1$ then $x_{ij} = 1$ and $x_{kl} = 1$ by constraints (1)–(2).

Therefore, $y_{ij,kl} = x_{ij}x_{kl}$ when all variables are binary. Hence, the QLOP can be written as the following integer linear program.

$$\begin{aligned}
& \text{maximize} && z = \sum_{i \neq j} a_{ij}x_{ij} + \sum_{i \neq j} \sum_{k \neq l} b_{ij,kl}y_{ij,kl} \\
& \text{subject to} && x_{ij} + x_{ji} = 1, && \forall i < j, \\
& && x_{ij} + x_{jk} + x_{ki} \leq 2, && \forall i < j, i < k, j \neq k, \\
& && y_{ij,kl} \leq x_{ij} && \forall i \neq j, k \neq l, \\
& && y_{ij,kl} \leq x_{kl} && \forall i \neq j, k \neq l, \\
& && y_{ij,kl} \geq x_{ij} + x_{kl} - 1 && \forall i \neq j, k \neq l, \\
& && x_{ij} \in \{0, 1\}, && \forall i \neq j, \\
& && y_{ij,kl} \in \{0, 1\}, && \forall i \neq j, k \neq l.
\end{aligned}$$

Modeling the QLOP as a integer linear program allows us to solve using relaxation, cutting planes, and branch-and-bound methods, which utilize linear programming techniques and theory. However, this linear programming model comes with serious computational drawbacks.

- We have lost the polyhedral structure of the LOP, which has a tight relaxation and lots of known valid inequalities and cutting planes.
- The LP relaxation degrades significantly with the introduction of the variables $y_{ij,kl}$ since the relaxation of constraints (1)–(3) does not represent the product $x_{ij}x_{kl}$.
- The degraded relaxation makes it harder to design effective cuts or to guide branching.
- The number of variables increases from $O(n^2)$ to $O(n^4)$, which significantly increases the size of the model.